



# **THOR – A Mobile, Free Space, Optical Network**

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**MIT Lincoln Laboratory**

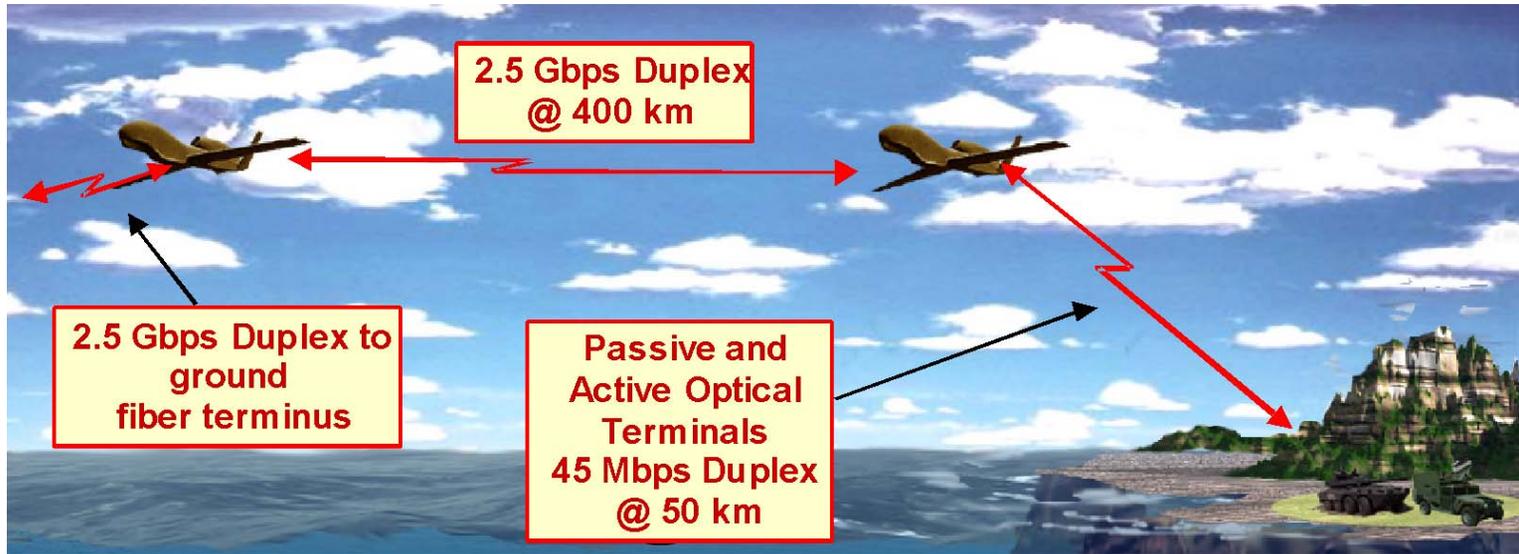


# Outline

- **Introduction**
- **The THOR optical network**
  - **Characteristics**
- **Major issues in free space optical, mobile networks**
  - **Physical layer**
  - **Network layer**
- **Potential solutions**
- **Summary**



# THOR Vision



- **Bring broadband communications to the theater of operations**
  - “Fat pipe into/out of theater”
- **Key characteristics of THOR network**
  - **Optical network**
    - Mobile, ad hoc network
    - Primarily airborne nodes
  - **Primarily digital data**
    - Sensor data

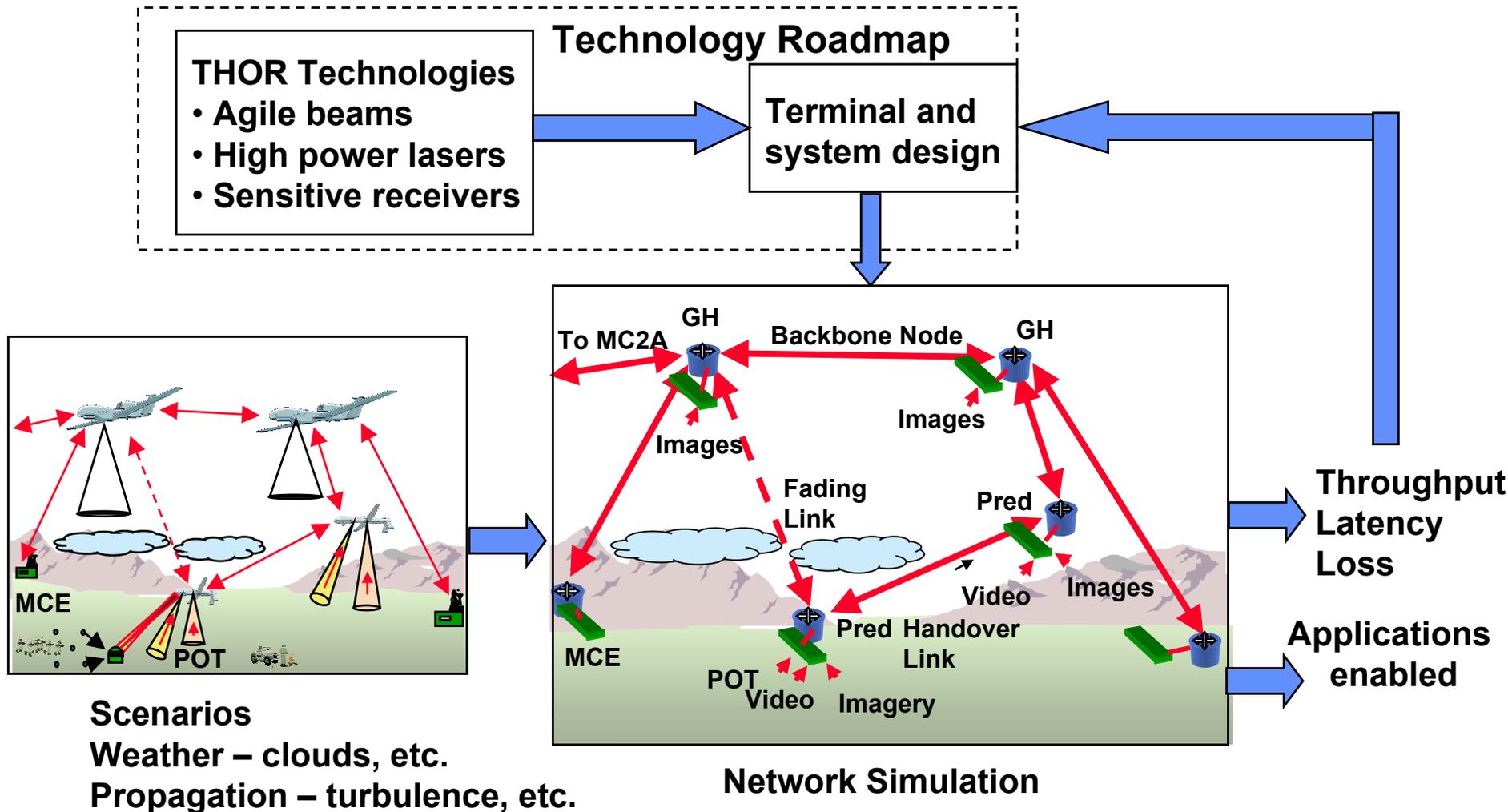


# THOR Notional “Requirements”

	Phase 1 - 2/03 Enabling Technologies	Phase 2A - 12/03 Subsystems	Phase 2 B - 10/04 Subsystems	Phase 3 - 10/05 System
<b>Latency</b> • Sensor feed • File transfer • Video and voice	< 2 seconds, 14 regeneration hops	< 1 second, 8 regeneration hops	< 500 msec, 6 regeneration hops	< 150 msec, 5 regeneration hops Sufficient for video and voice over 400 km
<b>Active Link Performance</b>	<ul style="list-style-type: none"> <li>• Data rate 2.0 Gbps</li> <li>• BER 10-9</li> <li>• Range 100 km</li> <li>• Link margin 5 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 2.0 Gbps</li> <li>• BER 10-9</li> <li>• Range 200 km</li> <li>• Link margin 6 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 8.0 Gbps</li> <li>• BER 10-9</li> <li>• Range 300 km</li> <li>• Link margin 24 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 8.0 Gbps</li> <li>• BER 10-9</li> <li>• Range 400 km</li> <li>• Link margin 33 dB</li> </ul>
<b>Passive Link Performance</b>	<ul style="list-style-type: none"> <li>• Data rate 200 Mbps</li> <li>• BER 10-9</li> <li>• Range 12 km</li> <li>• Link margin 15 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 200 Mbps</li> <li>• BER 10-9</li> <li>• Range 25 km</li> <li>• Link margin 17 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 800 Mbps</li> <li>• BER 10-9</li> <li>• Range 37 km</li> <li>• Link margin 15 dB</li> </ul>	<ul style="list-style-type: none"> <li>• Data rate 800Mbps</li> <li>• BER 10-9</li> <li>• Range 50 km</li> <li>• Link margin 20 dB</li> </ul>



# System Engineering and Network Architecture





# How Is THOR Used?

- **THOR is only part of the entire theater communications network**
  - **THOR optical links do not replace RF links**
- **THOR supports the extraction of extremely broadband data from sensors such as SAR and multispectral imagers**
  - **The largest fraction of THOR network bandwidth is associated with sensor data streams**
- **THOR optical terminals are at major command levels**
- **THOR network cost will be driven by the number of air vehicles required and the complexity and number of node ports required per air vehicle**



# THOR Physical Layer Issues

- **Available telecommunications technology**
  - Lasers, modulators, amplifiers, detectors, telescope, beam steering
  - Develop THOR specific optical communications technology
    - High power laser amplifiers, sensitive receivers, advanced beam steering techniques, passive optical terminal
- **Atmospheric transmittance**
  - Select waveband to avoid atmospheric absorption loss and dispersion
  - Robust links
- **Atmospheric turbulence**
  - Minimize aperture or use adaptive optics
  - Interleaving and coding
  - Robust links
- **Aircraft induced turbulence**
  - Aperture location
  - Field of regard
- **Cloud and terrain blockage**
  - Types and numbers of airborne nodes
  - Placement of airborne nodes – three dimensional diversity
  - Acquisition and tracking of airborne nodes



# Building Robust Links

- **Use high power transmitters**
- **Nearly all communication links operate with the transmitter beam larger than the receiver aperture (“Far field link”)**
  - Free space loss equal to the ratio of the illuminated area to the receiver aperture area
- **Optical links may be operated in a far field link or a near field link**
  - Near field link transmitter aperture just fills the receiver aperture thus minimizing the free space loss
- **Near field link requires dynamic focusing and precise tracking**
  - If the Fried coherence diameter is smaller than the aperture, then an adaptive optic system is required
  - Aircraft integration may preclude near field links



# Overcoming Atmospheric Turbulence

- **If possible operate at elevation angles  $>$  than  $\sim 40$  degrees**
  - **Minimizes both transmission losses and turbulence effects**
- **If sufficient link margin exists, build the transceiver terminal so that the aperture diameter is smaller than the Fried coherence diameter**
  - **Reasonable strategy for high altitude links**
  - **Reduces cost and complexity of the terminal**
- **Utilize interleaving and coding to build margin against turbulence fades**
- **Low altitude, horizontal paths may require adaptive optics to overcome the effects of turbulence**
  - **Consider a near field link to build a very robust link margin**

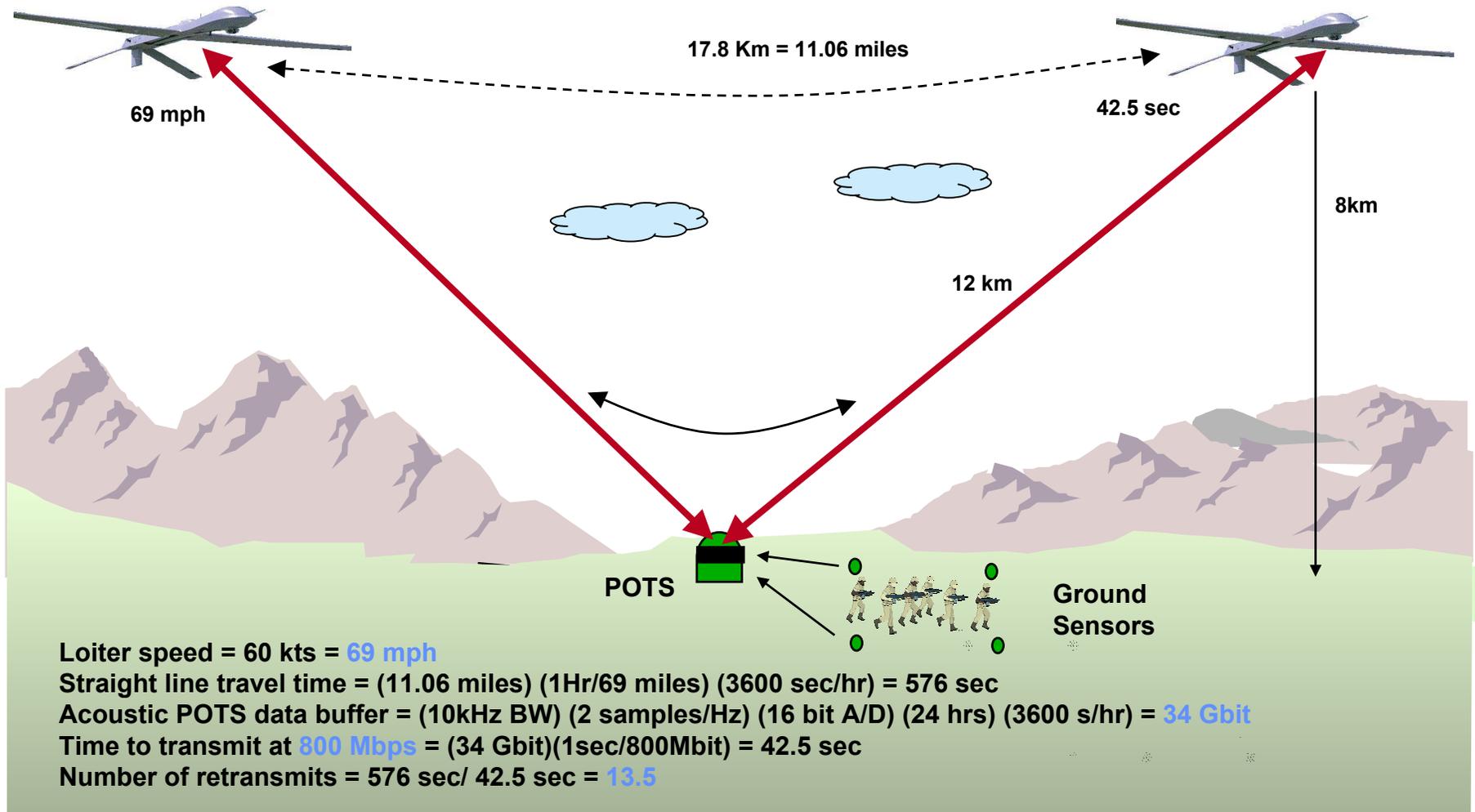


# Overcoming Cloud, Fog and Terrain Blockages

- **Broken clouds**
  - Transmit THOR signals through openings in clouds
- **Cloud layer**
  - Build parallel links below and above cloud layer
  - Communicate between layers through an opening in the clouds
  - Fly under the clouds, “harvest” stored data and physically fly back up to restore network connection – POTS scenario
- **Cloud undercast**
  - Air vehicle towed passive optical terminals
    - Extend towed terminal below the undercast to communicate below and above cloud layer
  - Historic precedent in towed decoys, towed “cloud cars”
    - WW I - 1000 meter cables were used with cloud cars
- **Fog and cloud overcast**
  - Aerostat with fiber optic cable to optical terminal
    - Aerostat flies above cloud layer
  - Historic precedent in aerostat radars along southern border of the continental US
    - Now – 7600 m cables used with TARS radar aerostat
    - Aerostat hovers at 4600 meters



# Passive Optical Terminal Scenario – “Harvesting” Stored Data Files





# Tethered Aerostat Radar System (TARS)

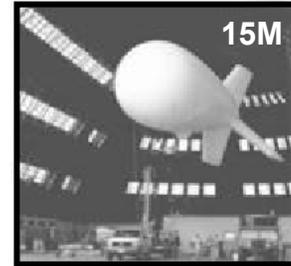
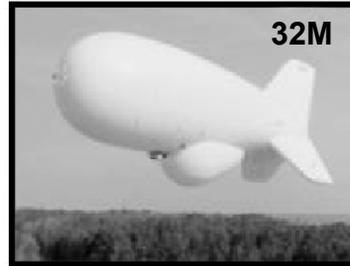
- **Static radar site**
- **First deployed in 1984**
- **Two aerostat sizes**
  - 275,000 cu ft – 32M aerostat
  - 420,000 cu ft – 71 M aerostat
- **8 sites**
- **Inventory – 12 + spares**
- **10,000 to 15,000 foot operating altitude**
- **1200 and 3400 lb payloads**
- **Stable in winds up to 65 knots**
- **Average Uptime ~ 60%, best site ~ 84%**
- **Cost per site - \$ 2.8 M**



**71 M Aerostat**

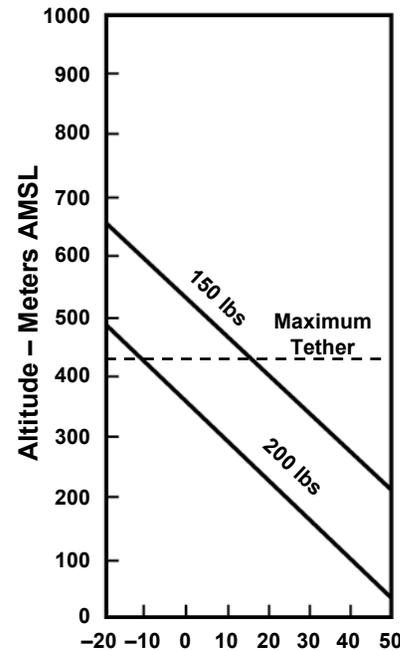
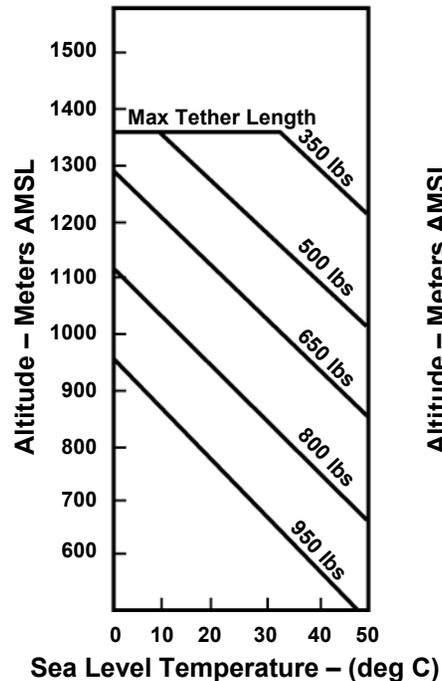
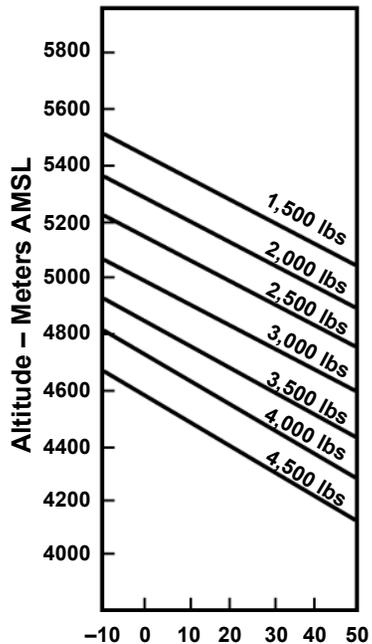


# TCOM Airship Specifications



## 71M Aerostat

- Operational to 70 kts
- 30-day flight duration



## 32M Aerostat

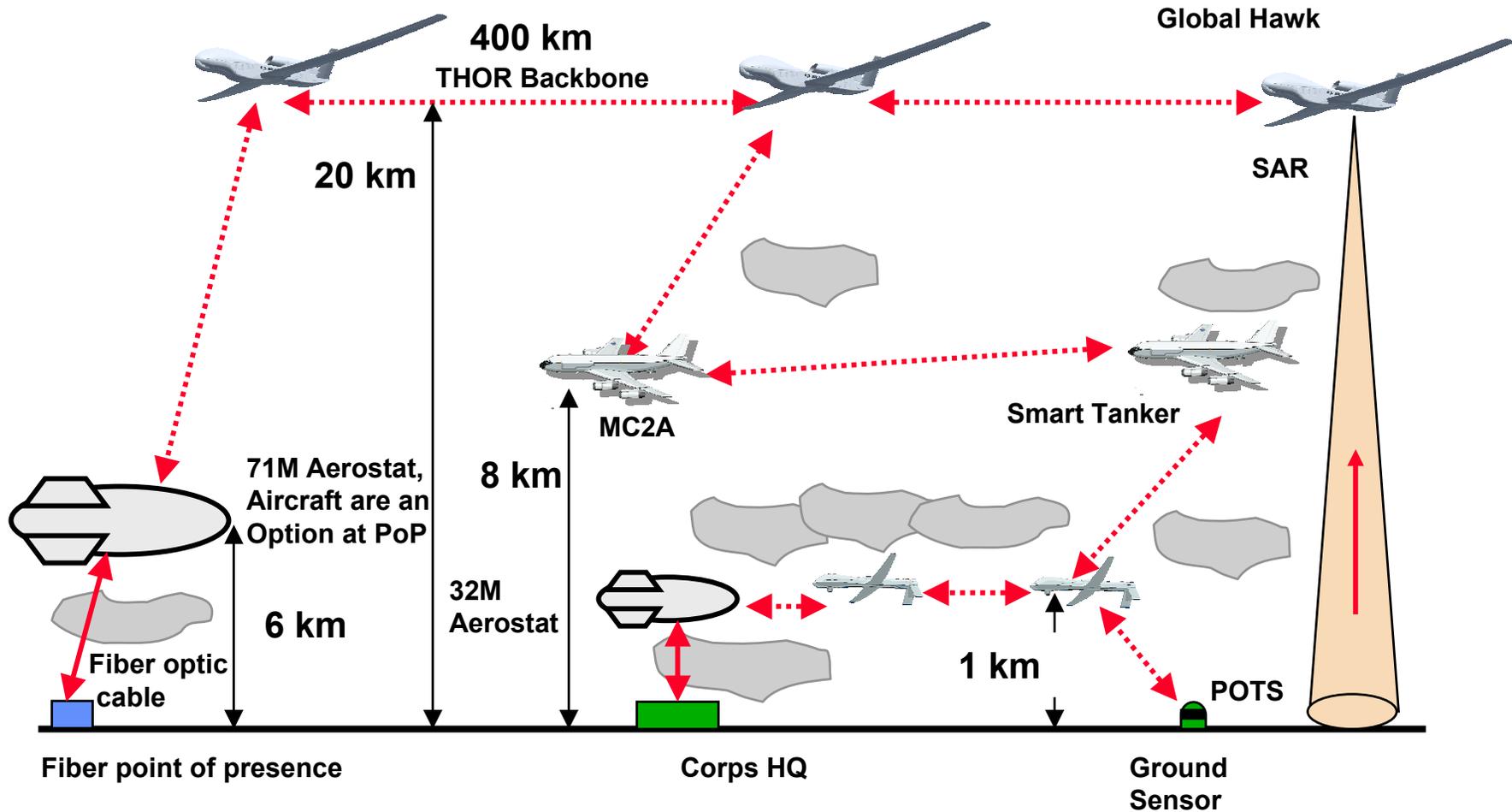
- Operational to 50 kts
- 14-day flight duration

## 15M Aerostat

- Operational to 40 kts
- 5-day flight duration



# Link Geometries





# THOR Network Layer Issues - 1

- **Primary supported applications**
  - **Streaming, high rate sensors**
  - **File transfer**
  - **“Instant messaging”**
  - **Web access**
  - **Email**
  - **Voice**
- **Dynamic topology**
  - **Nodes are deployed, move, go out of service**
  - **Dynamically establish and tear down links**
  - **Adjust to optimize service quality and resource utilization**



# THOR Network Layer Issues - 2

- **Handover**
  - **Level of transparency**  
Network level as in MobileIP (transparent to the application)
  - **Sequencing**  
Make before break requires multiple ports  
Buffering
  - **Data handling**  
Lost data or long disconnects can impact throughput and latency  
Buffer overflow or congestion control algorithms in the routers  
TCP congestion control mechanisms  
Avoid losing any data or permit higher layers of the stack to recover from losses
- **Quality of service (QoS)**
  - Latency
  - Throughput
  - Reliability
- **Security**
  - Denial of service – during acquisition
  - Compromise of a node
  - Authentication of handoffs, acquisition, etc.



# Summary

- **THOR free space, mobile optical network potentially can bring broadband data into and out of the military theater of operations**
- **THOR has unique terminal concepts and platforms**
  - **Terminals should be modular, with the greatest variation seen in the free space optics subsystem**
  - **Passive optical terminal, in the form of a modulated retroreflector, can be used in a low cost store and forward application as well as an optical relay**
- **Primary network cost driver is associated with overcoming network blockages due to clouds**