

**NORTHROP GRUMMAN**

DEFINING THE FUTURE

*Electronic Systems*

**“KASSPER Technology  
for the Advanced Strike Fighter”**

**KASSPER Workshop  
Clearwater, FL**

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# KASSPER Technology for the Advanced Strike Fighter (ASF)

## Outline

- Introduction
- Real and Simulated Test data
- Algorithms / Experiments
  - STAP enhancement with auxiliary processes
    - Results on synthetic data
    - Results on real data from ASF prototype
  - Heterogeneous clutter
    - Analytical experiment
    - Synthetic data validation
- Summary



## GMTI in Advanced Strike Fighters

- Requires the ability to reliably detect, track, and precisely locate all-speed targets in challenging surface clutter environments:
  - Heterogeneous littoral clutter scenarios
  - Rapidly changing dynamic terrain relief
  - Concentrated regions of background traffic
  - Constrained ingress routings to minimize known threats
- Needs to maintain target tracking throughout planning and attack phases
- Requires simultaneous SAR and GMTI performance during platform and target tactical maneuvers





# Additional Advanced Strike Fighter Challenges

- Significant MDV and geolocation challenges under off-boresight conditions with forward-facing up-tilted arrays
- Optimal utilization of available on-board and intra-sensor information sources needed due to:
  - Limited on-board database capacity
  - Bandwidth-limited access to off-board knowledge
  - Weight/volume constrained signal processor





# The Northrop Grumman Electronic Systems KASSPER Program Effort Focuses On:

- **Enhancing GMTI Performance for Advanced Strike Fighters by evaluating the benefits of:**
  - **Using on-board sensor knowledge (INS, RF waveform)**
  - **Recognizing and excising dense moving target clusters from sample background statistics**
  - **Using SAR-based prescreening of heterogeneous clutter containing large stationary discretets**
- **Leveraging the library of GMTI scans collected by our multi-channel 4th Gen AESA prototype radar**
- **Documenting the resultant knowledge-aided signal processing architecture by:**
  - **Analyzing and quantifying KASSPER benefits under realistic and challenging RF conditions**



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## Northrop Grumman Electronic Systems is Actively Involved in the Design & Development of High Performance GMTI Systems for Many Applications

Program	Sponsor	Description
Joint STARS AN/APY-7	US Air Force	Design, develop and produce long-range MTI and SAR radar utilizing adaptive processing technology
F-35 Joint Strike Fighter (JSF)	US Air Force, Navy & Marines	System development and demonstration phase of next generation fighter radar
MP-RTIP	US Air Force	Next generation multiple-platform GMTI/SAR surveillance system
F/A-22 Raptor	US Air Force	Production radar system on premier air-superiority fighter; P <sup>3</sup> I adding advanced GMTI capabilities
SBR ESA/OBP Concept Development	US Air Force & NRO	Design and analyze SAR and MTI modes for implementation on SBR systems

**Northrop Grumman Electronic Systems has the optimal blend of GMTI experience to successfully perform the KASSPER program activities and to apply our results to many sensor configurations**

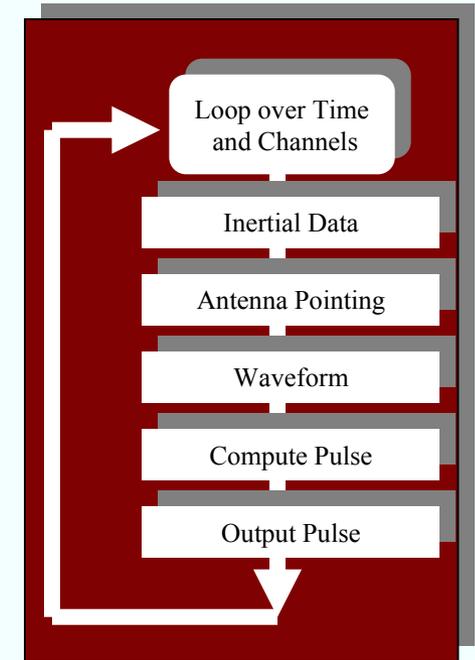


## **IQ Data Generator . . .**

- **Generate IQ data for testing and evaluating algorithms**
  - real-time with closed loop control
  - off-line processing
- **Customizable**
  - accommodates a variety of waveform timelines
  - noise jammers
  - stretch and non-stretch waveforms
- **Written in C for speed, although a MATLAB re-hosting may be useful**
- **Wide Program Application:**
  - MMRS Digital Subsystem Lab
  - JSF Demo - Digital Target Simulator
  - APTI / FOPEN / JSF / SBR / MP-RTIP

- **User Inputs:**
  - aircraft geometry
  - radar parameters
  - clutter and moving target arrangement
  - dynamic waveform parameters
- **Outputs:**
  - Binary files, one per receiver channel
  - Data arranged in pulse sequence order
  - Time tag, AGC, A/D start time, ...
  - 32 bit I/Q samples

- **Process:**



**. . . allows high fidelity testing of KASSPER algorithms**

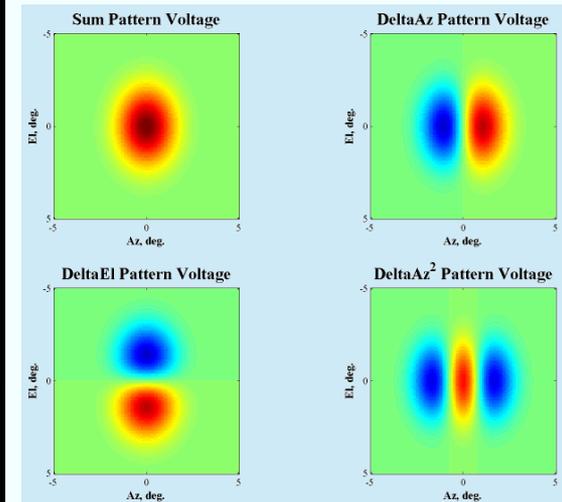


# IQ Data Generator . . .

Aircraft Parameter		Antenna Parameter	
Altitude	8 km	<b>Transmit</b>	
Slant Range	37 km	$G_{XMT}$	37 dB
Speed	109 m/s	BW_3dB_AZ	1.3 deg
		BW_3dB_EL	1.7 deg
Radar Parameter			
$f$	9.7 GHz	<b>Receive</b>	
$P_T$	8 kW	$G_{REC}$	37 dB
Duty	.4%	BW_3dB_AZ	1.3 deg
		BW_3dB_EL	1.7 deg
Waveform Parameter			
PRF	1.428 kHz	<b>Clutter Parameter</b>	
$T_c$	100 ms	Discrete Clutter Model	
Range resol.	~ 1 m		



**ASF Antenna Patterns**



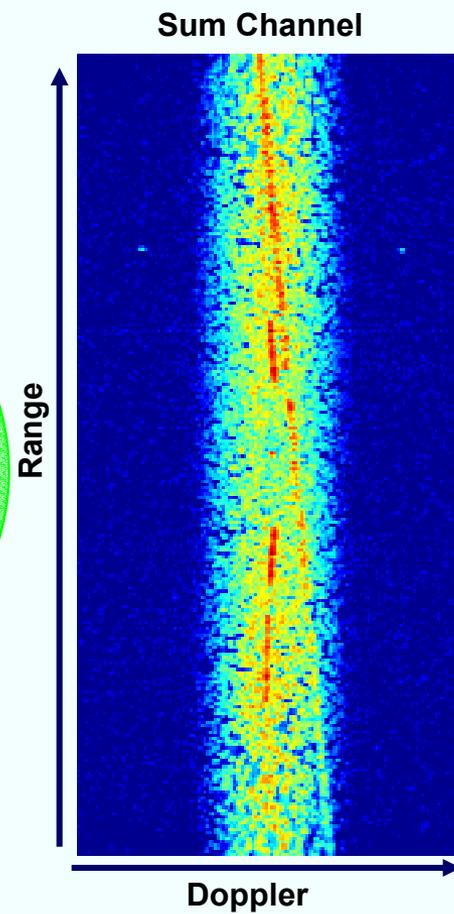
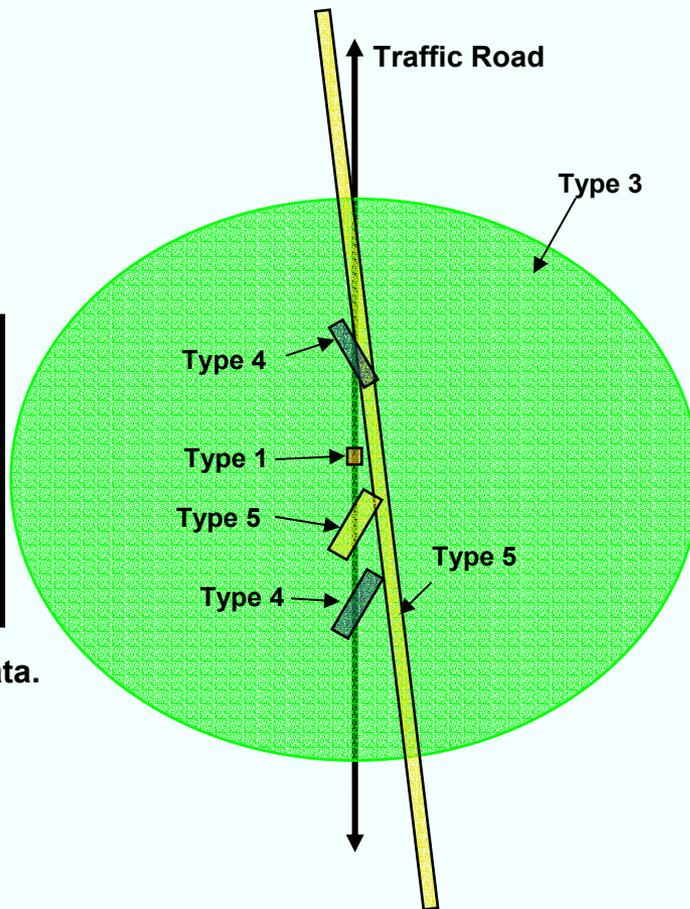
. . . emulates ASF environment, beam patterns and waveforms



# Typical Output from the IQ Generator

Clutter Type	Amplitude	Distribution
1	Constant	Uniform
3	Rayleigh	Gaussian
4	Rayleigh	Uniform
5	Gamma	Uniform

\*Type 2 clutter: Based on real SAR image data.



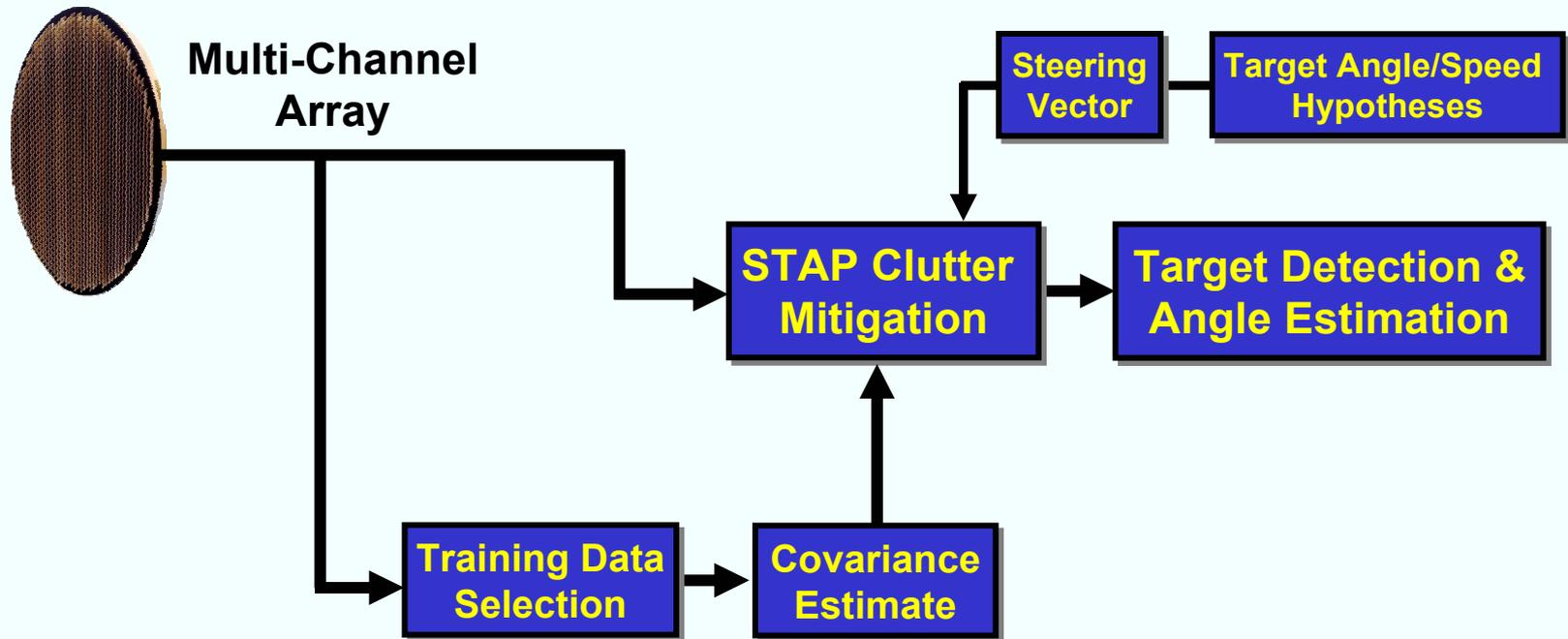


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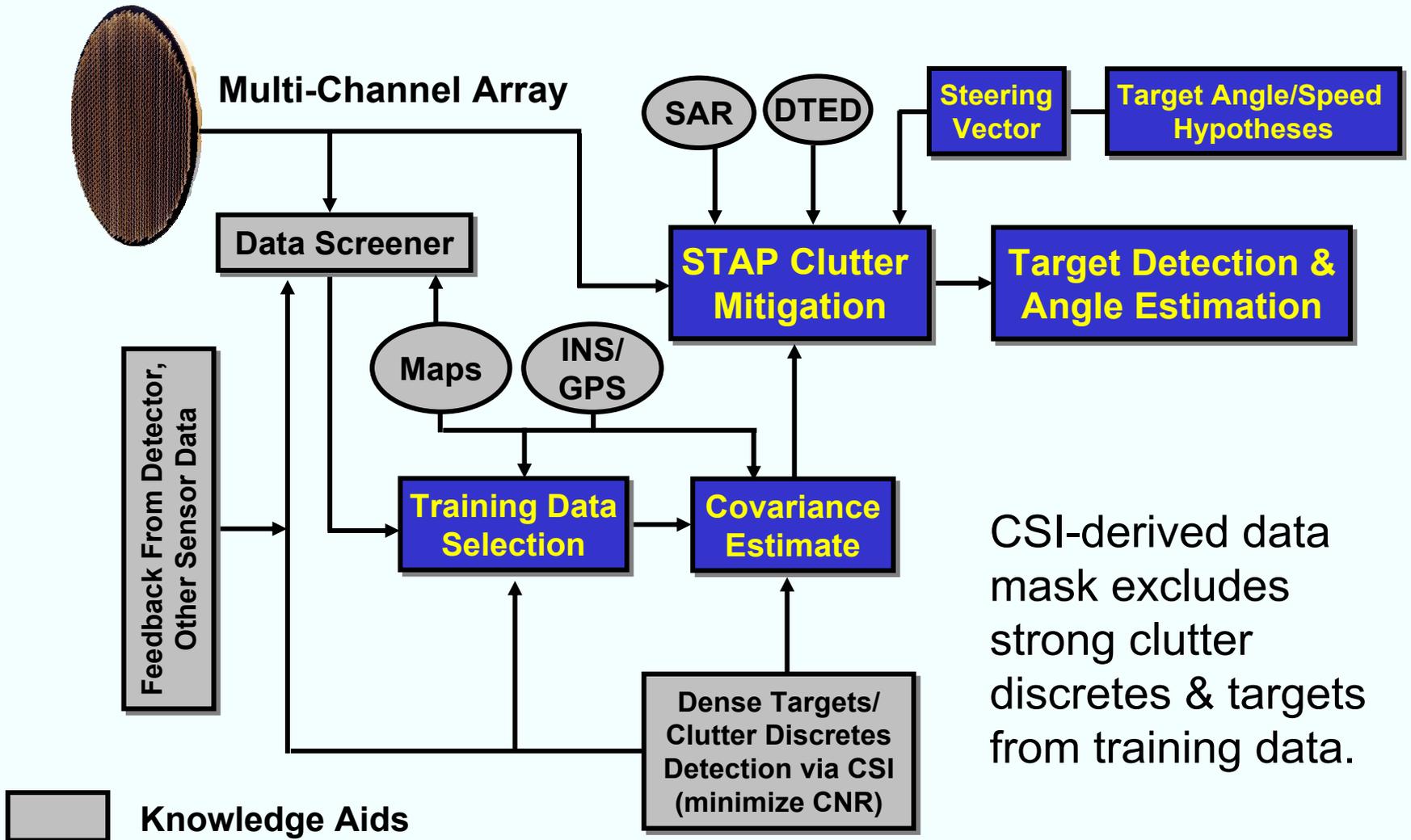


## Traditional STAP Architecture



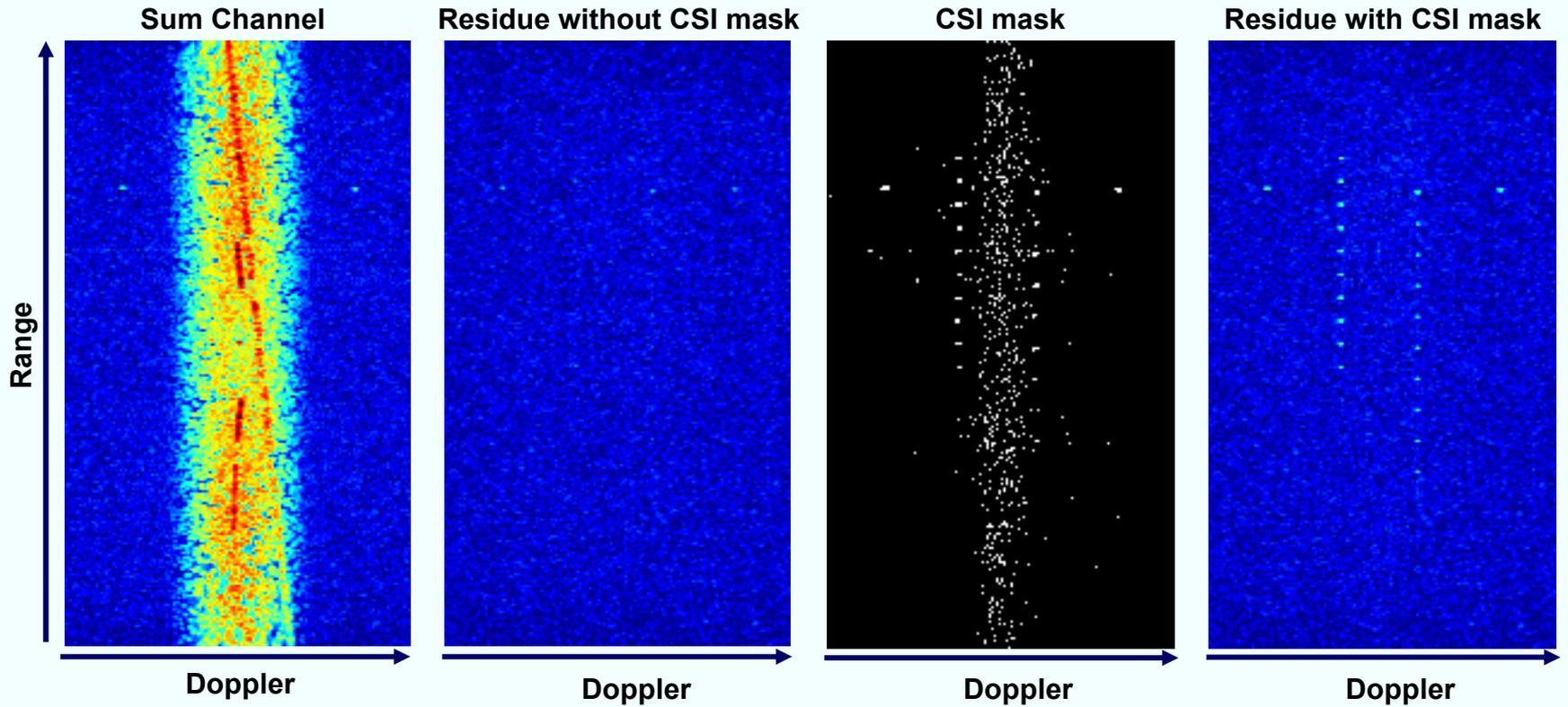


# Intra-Sensor Knowledge Aids Traditional STAP Architecture



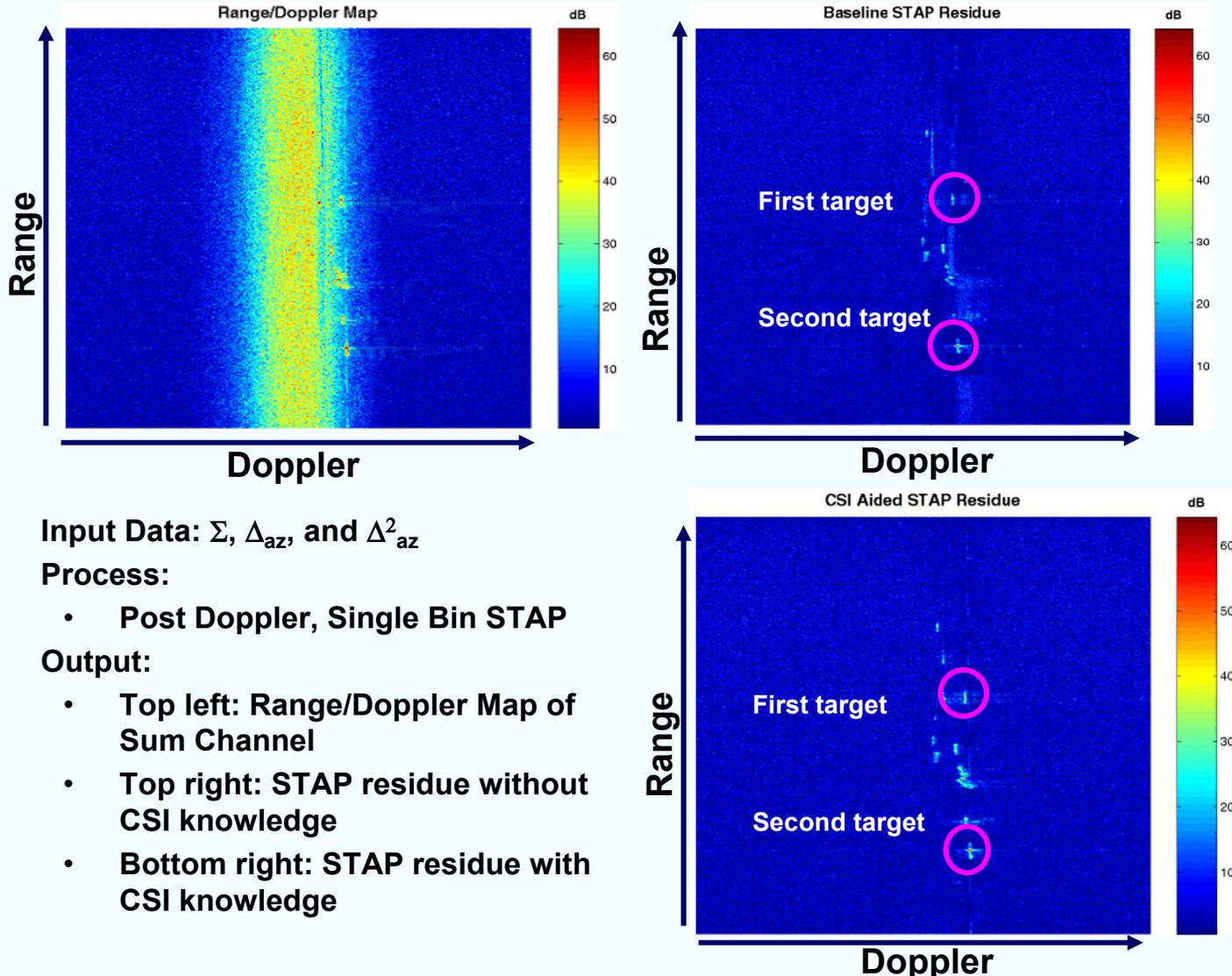


# SNR Improvement with CSI Knowledge Using Simulated data





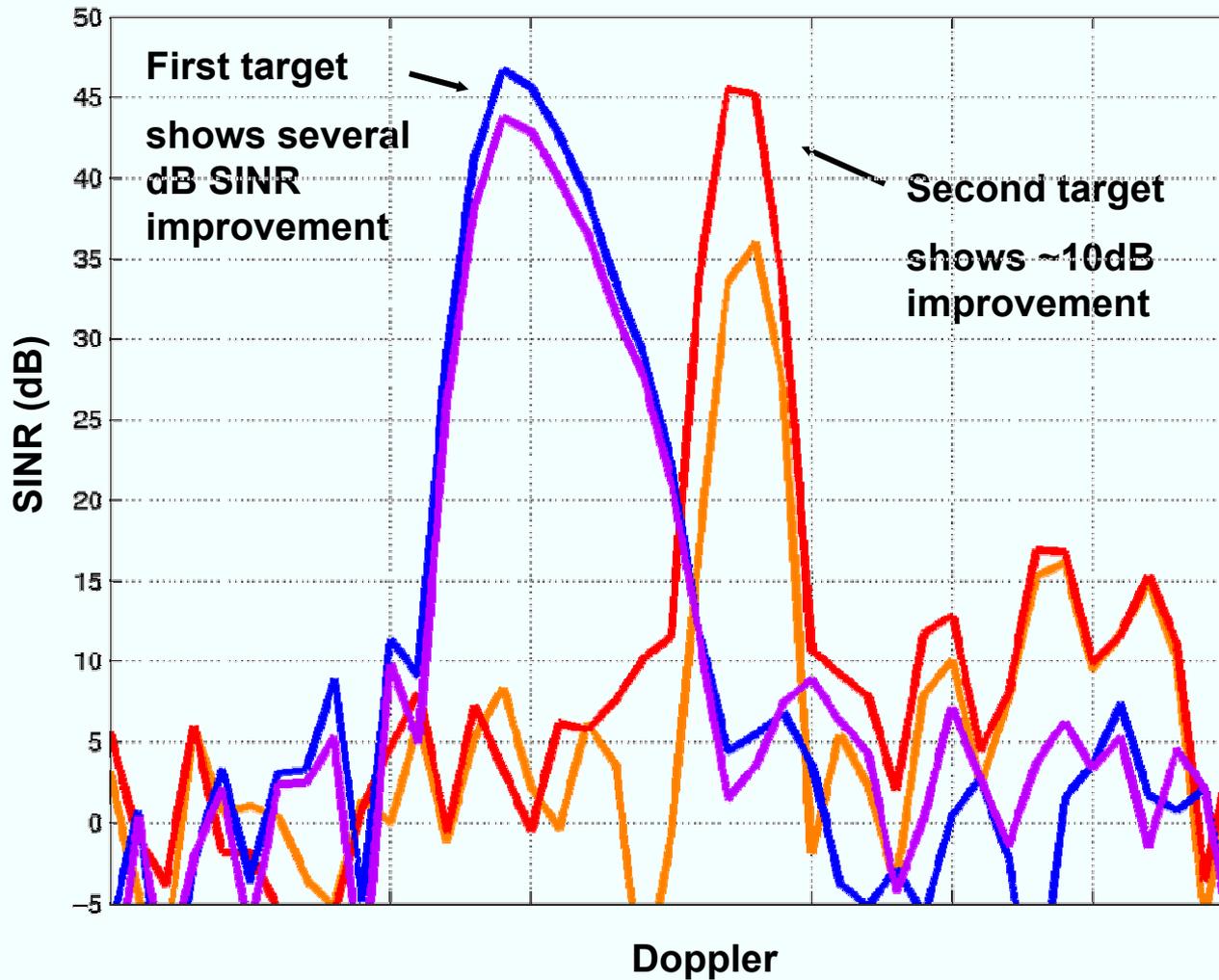
# SNR Improvement with CSI Knowledge Using Real Data



- **Input Data:**  $\Sigma$ ,  $\Delta_{az}$ , and  $\Delta_{az}^2$
- **Process:**
  - Post Doppler, Single Bin STAP
- **Output:**
  - Top left: Range/Doppler Map of Sum Channel
  - Top right: STAP residue without CSI knowledge
  - Bottom right: STAP residue with CSI knowledge



# CSI-Aided STAP Residue Shows Improved SINR





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## Effect of Non-Homogeneous (NH) Clutter

- Compare the effects of sensed (observed) versus actual Clutter to Noise Ratio (CNR) which differ by some CNR error

$$\hat{\alpha}_{\text{dB}} = \alpha_{\text{dB}} + (\text{CNR error})_{\text{dB}}$$

$$\text{SINR}_{\text{ACTUAL}} = \frac{\mathcal{G}(\theta_s)}{\alpha_{\text{V/V}} \mathcal{G}(\theta_{\text{RFI}}) + N}$$

$$\text{SINR}_{\text{SENSED}} = \frac{\mathcal{G}(\theta_s)}{\hat{\alpha}_{\text{V/V}} \mathcal{G}(\theta_{\text{RFI}}) + N}$$

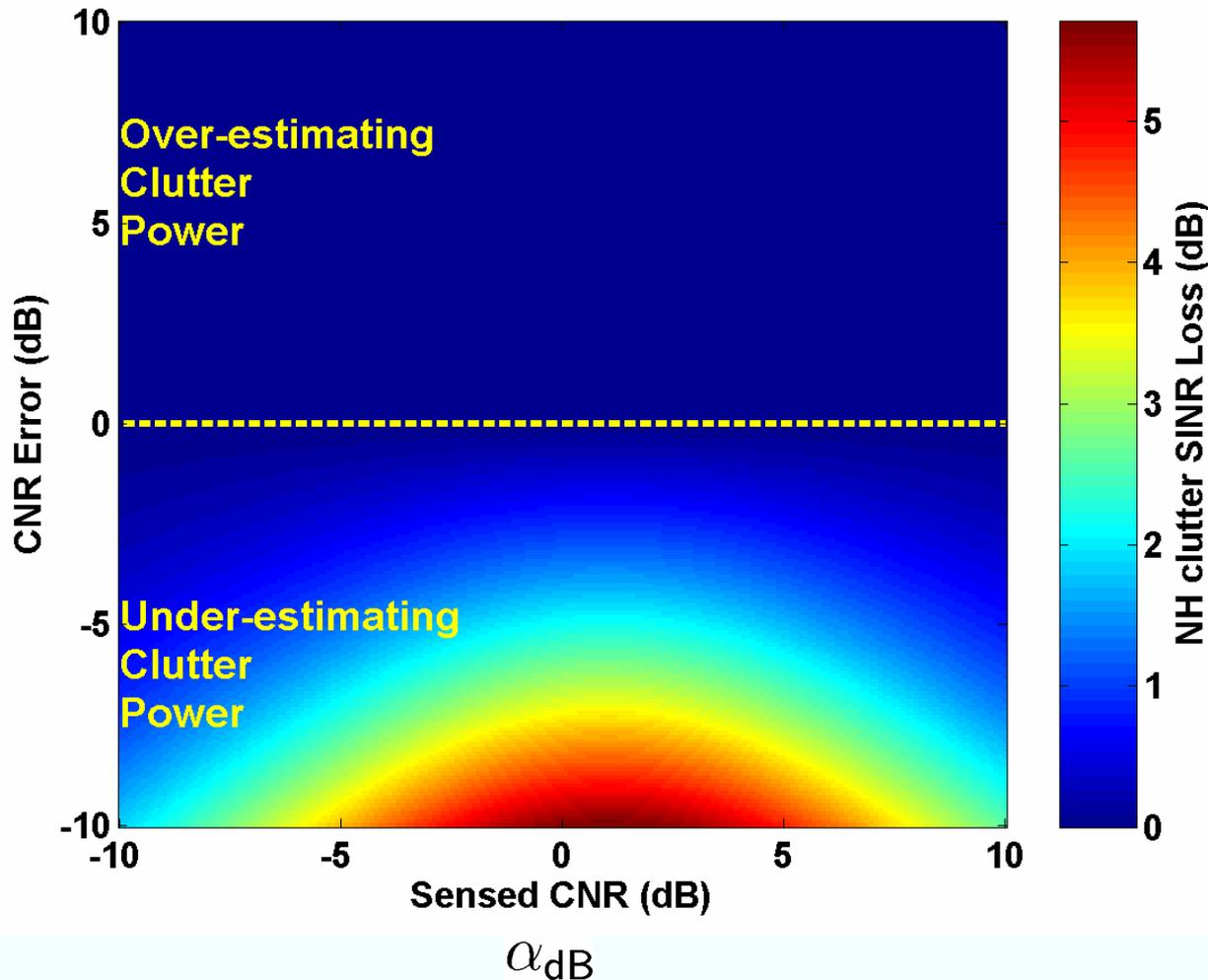
$$\text{NH CLUTTER LOSS} = \text{SINR}_{\text{ACTUAL}} - \text{SINR}_{\text{SENSED}}$$

for pattern gain adapted to sensed RFI power



# Non-Homogeneous Clutter Loss

This shows that it's better to overestimate the power of the RFI source.

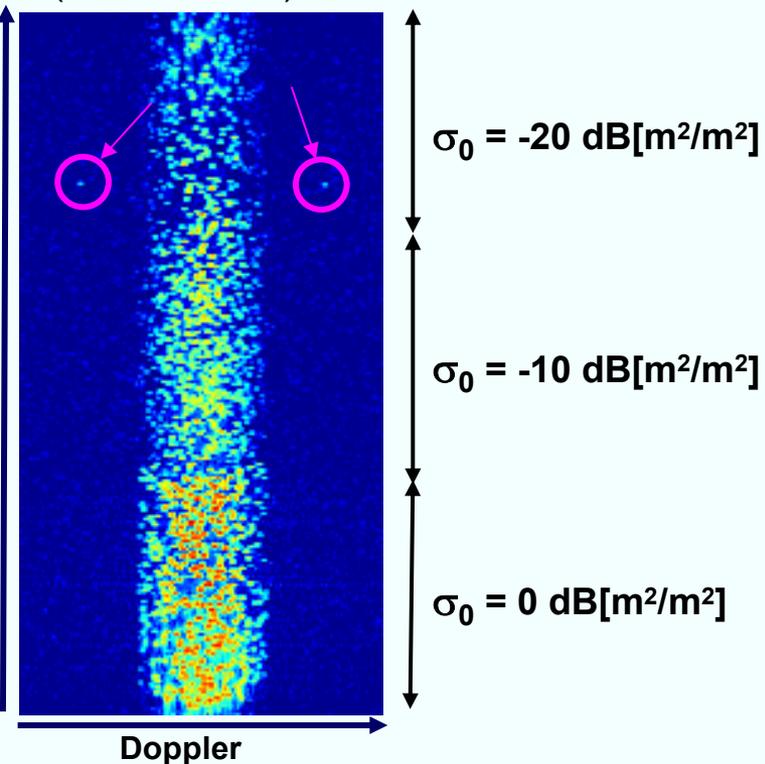


Resultant SINR loss is worse due to underestimating clutter power

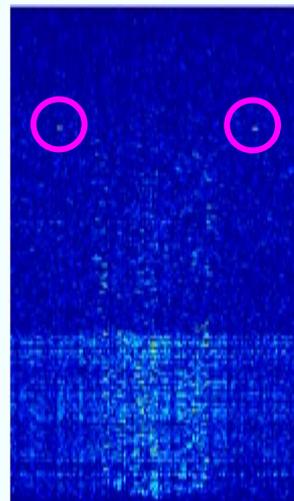


# Training in Heterogeneous Clutter Environment Demonstrates Effects of Power-Weighted Training

Heterogeneous Clutter  
Scenario For STAP Data  
Training Selection  
(Sum channel)



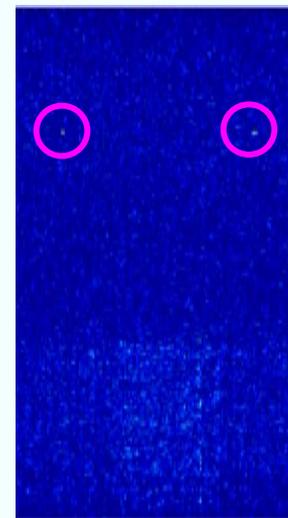
Train On **Weak** Clutter



Doppler

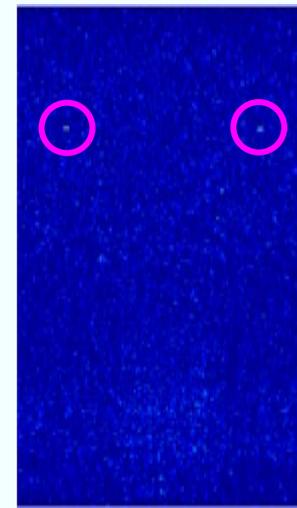
Bad to  
under-estimate  
clutter power.

Train On **Moderate** Clutter



Doppler

Train On **Strongest** Clutter

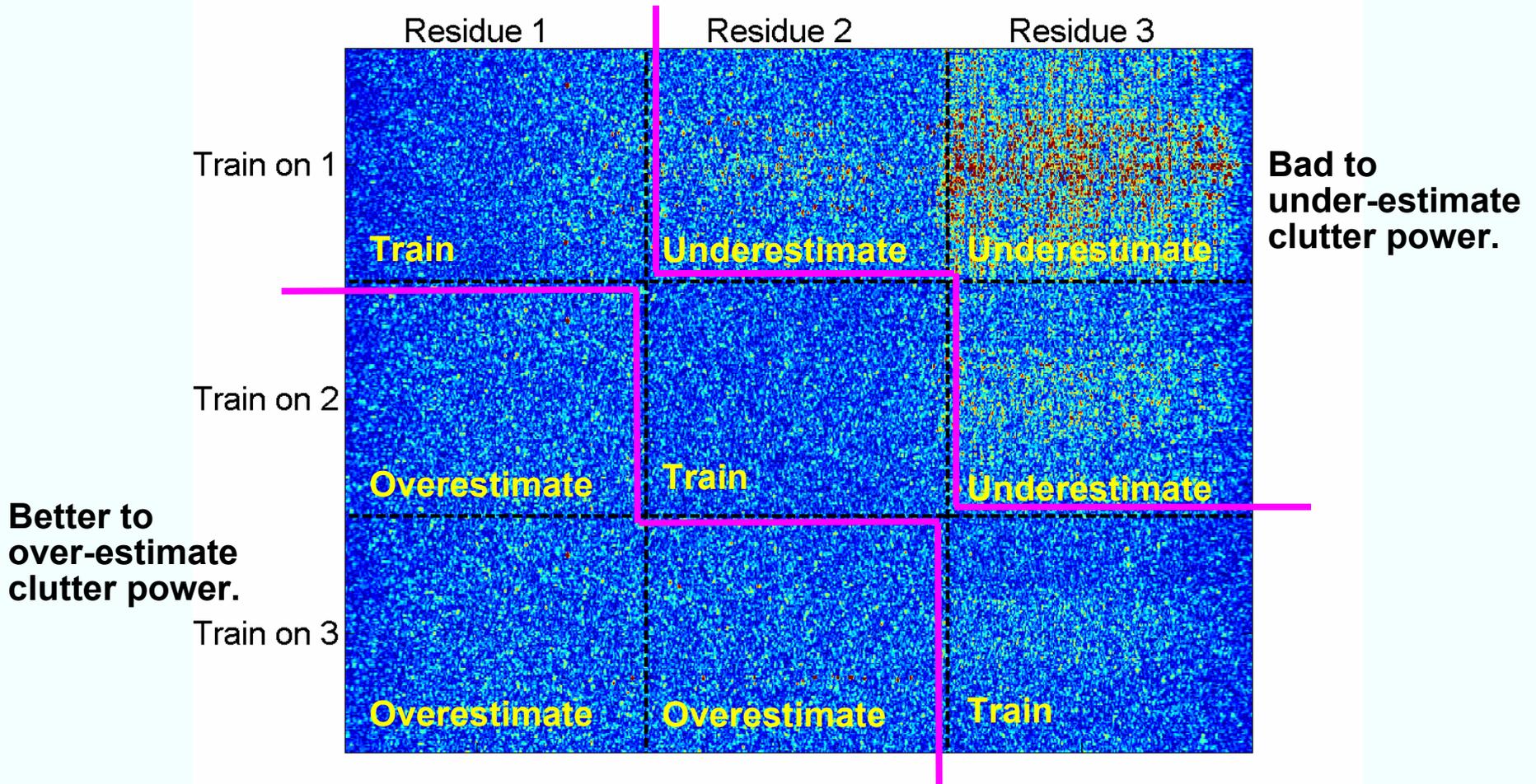


Doppler

Better to  
over-estimate  
clutter power.



# Training in Heterogeneous Clutter Environment Demonstrates Effects of Power-Weighted Training





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## Summary: Current Status

- The need for knowledge aids for Advanced Multi-Mission Strike Fighters STAP/GMTI processing is well-established.
- I/Q simulation of synthetic data cubes for the Advanced Multi-Mission Strike Fighters includes heterogeneous clutter.
- Multi-pass CSI / STAP algorithm demonstrates improvement in SINR using both simulated and real radar data from ASF.
- Better clutter cancellation performance is attained when sensed clutter power matches actual.



## Summary: Future Work

- **Short term**
  - **Near real-time demo in JSF classified laboratory in Norwalk, CT.**
  - **Show STAP performance improvement using knowledge aids on synthetic and real data from the 4th Generation sensor.**
- **Long term**
  - **Implement KASSPER technologies into JSF GMTI architecture to enhance detection performance.**